

Selective cell-based smoothed finite element method using 10-node tetrahedral elements for large deformation of nearly incompressible solids

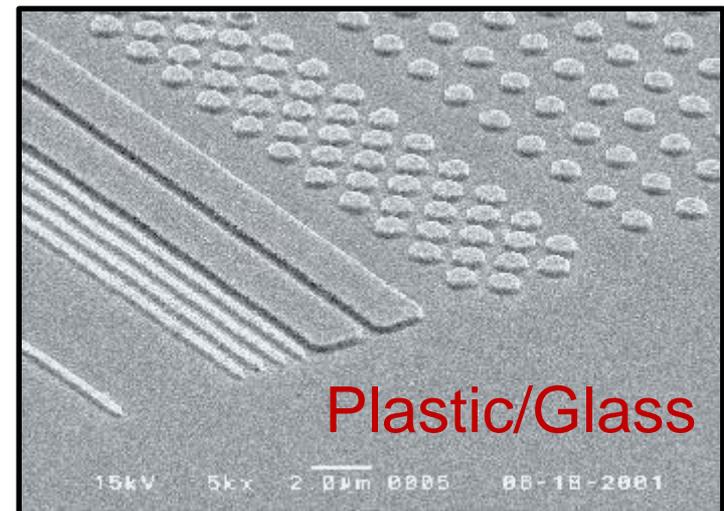
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Motivation

What we want to do:

- Solve **hyper large deformation** analyses accurately and stably.
- Treat complex geometries with **tetrahedral meshes**.
- Consider **nearly incompressible materials** ($\nu \simeq 0.5$).
- Support **contact** problems.
- Handle **auto re-meshing**.



Issues

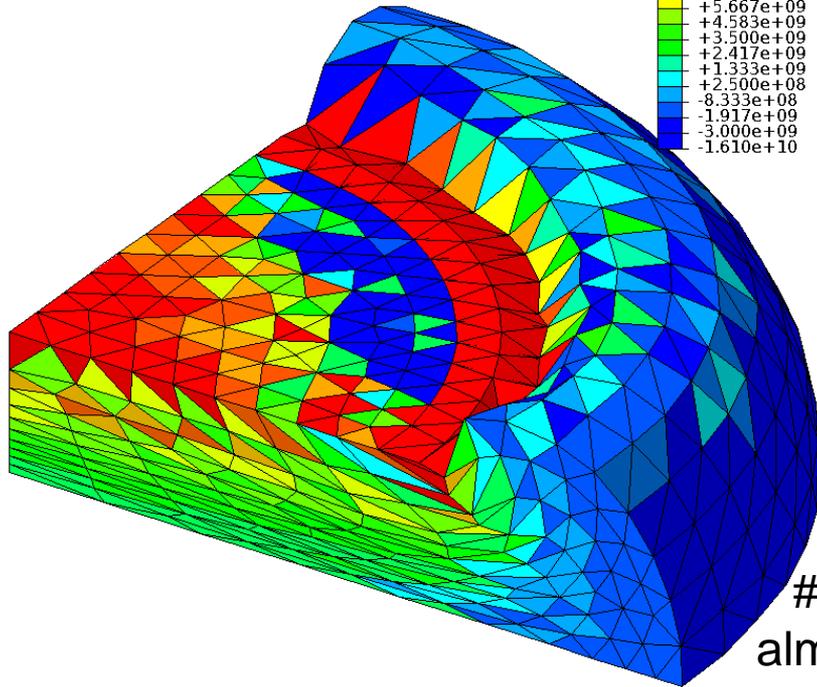
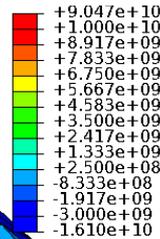
Conventional **tetrahedral (T4/T10)** FE formulations still have issues in accuracy or stability especially in **nearly incompressible** cases.

- 2nd or higher order elements:
 - ✗ Volumetric locking.
 - Accuracy loss in large strain due to intermediate nodes.
- B-bar method, F-bar method, Selective reduced integration:
 - ✗ Not applicable to tetrahedral element directly.
- F-bar-Patch method:
 - ✗ Difficulty in building good-quality patches.
- u/p mixed (hybrid) method:
(e.g., ABAQUS/Standard **C3D4H** and **C3D10MH**)
 - ✗ Pressure checkerboarding, Early convergence failure etc..
- F-bar type smoothed FEM (F-barES-FEM-T4):
 - ✓ Accurate & stable
 - ✗ Hard to implement in FEM codes.

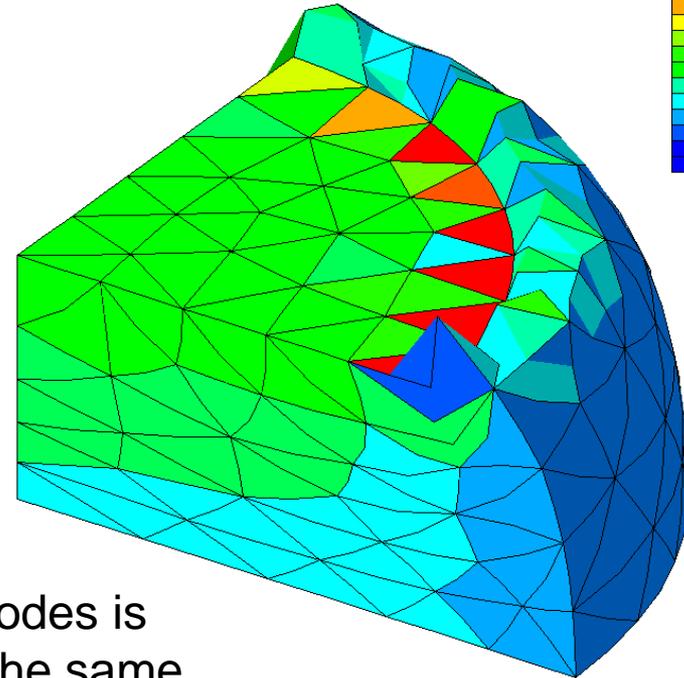
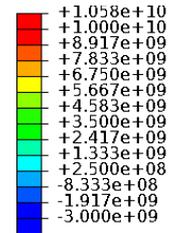
Issues (cont.)

E.g.) Compression of neo-Hookean hyperelastic body with $\nu_{ini} = 0.49$

Pressure



Pressure



of Nodes is almost the same.

1st order hybrid T4 (C3D4H)

- ✓ No volumetric locking
- ✗ Pressure checkerboarding
- ✗ Shear & corner locking

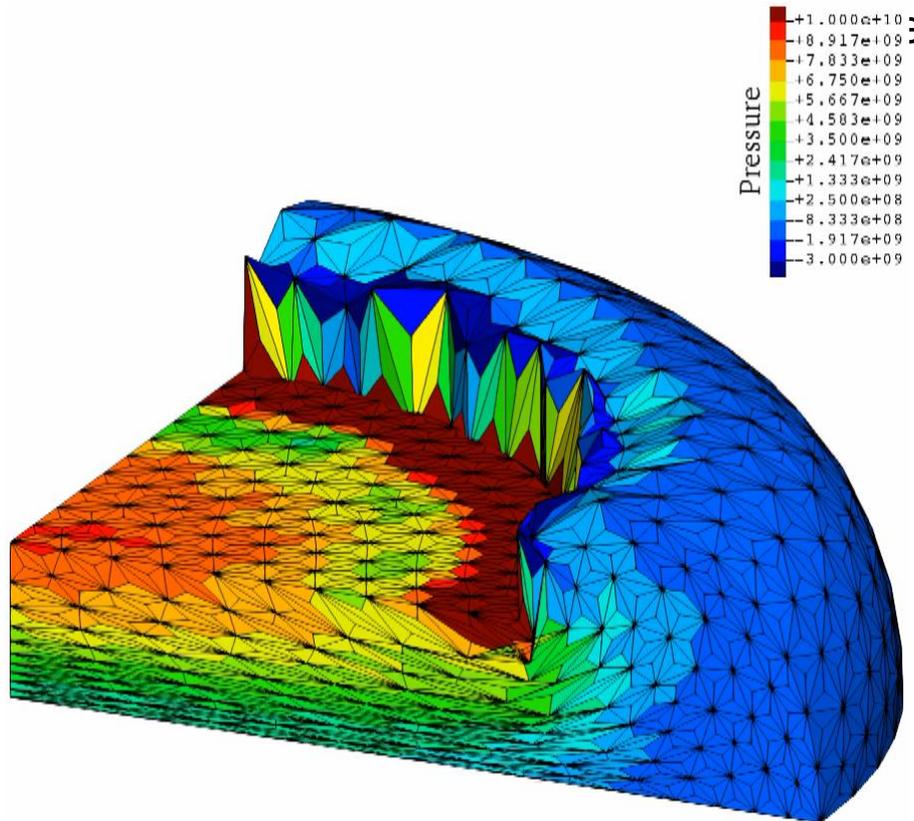
2nd order modified hybrid T10 (C3D10MH)

- ✓ No shear/volumetric locking
- ✗ Early convergence failure
- ✗ Low interpolation accuracy

Issues (cont.)

E.g.) Compression of neo-Hookean hyperelastic body with $\nu_{ini} = 0.49$

Same mesh
as **C3D4H**
case.



Although
F-barES-FEM-T4 is
accurate and stable,
X it cannot be
implemented in
general-purpose
FE software
due to the adoption
of ES-FEM.



F-barES-FEM-T4

- ✓ No shear/volumetric locking
- ✓ No corner locking
- ✓ No pressure checkerboarding

Another approach
adopting **CS-FEM**
with **T10** element
would be effective.

Objective

To propose an accurate and stable CS-FEM-T10, “**SelectiveCS-FEM-T10**”, and to implement it into general-purpose FE software.

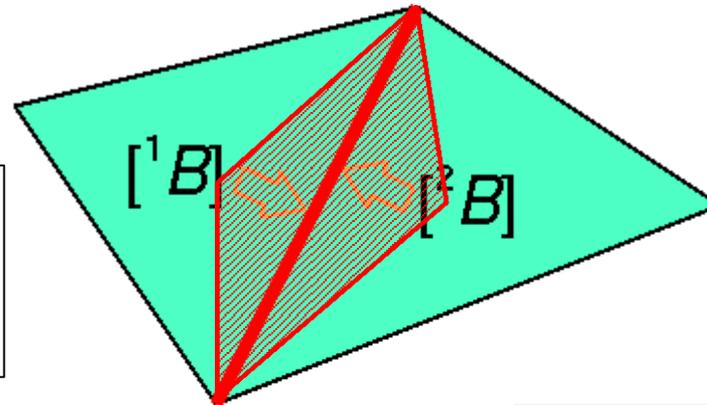
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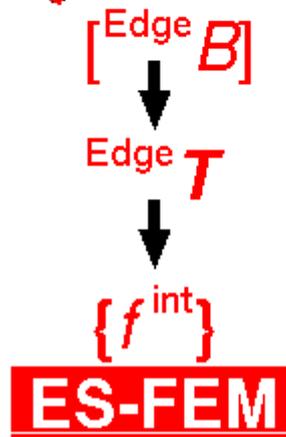
Formulation of SelectiveCS-FEM-T10

Brief Review of Edge-based S-FEM (ES-FEM)

- Calculate $[B]$ at each element as usual.
- Distribute $[B]$ to the connecting **edges** with area weight and build $[^{\text{Edge}}B]$.
- Calculate $F, T, \{f^{\text{int}}\}$ etc. in each **edge** smoothing domain.



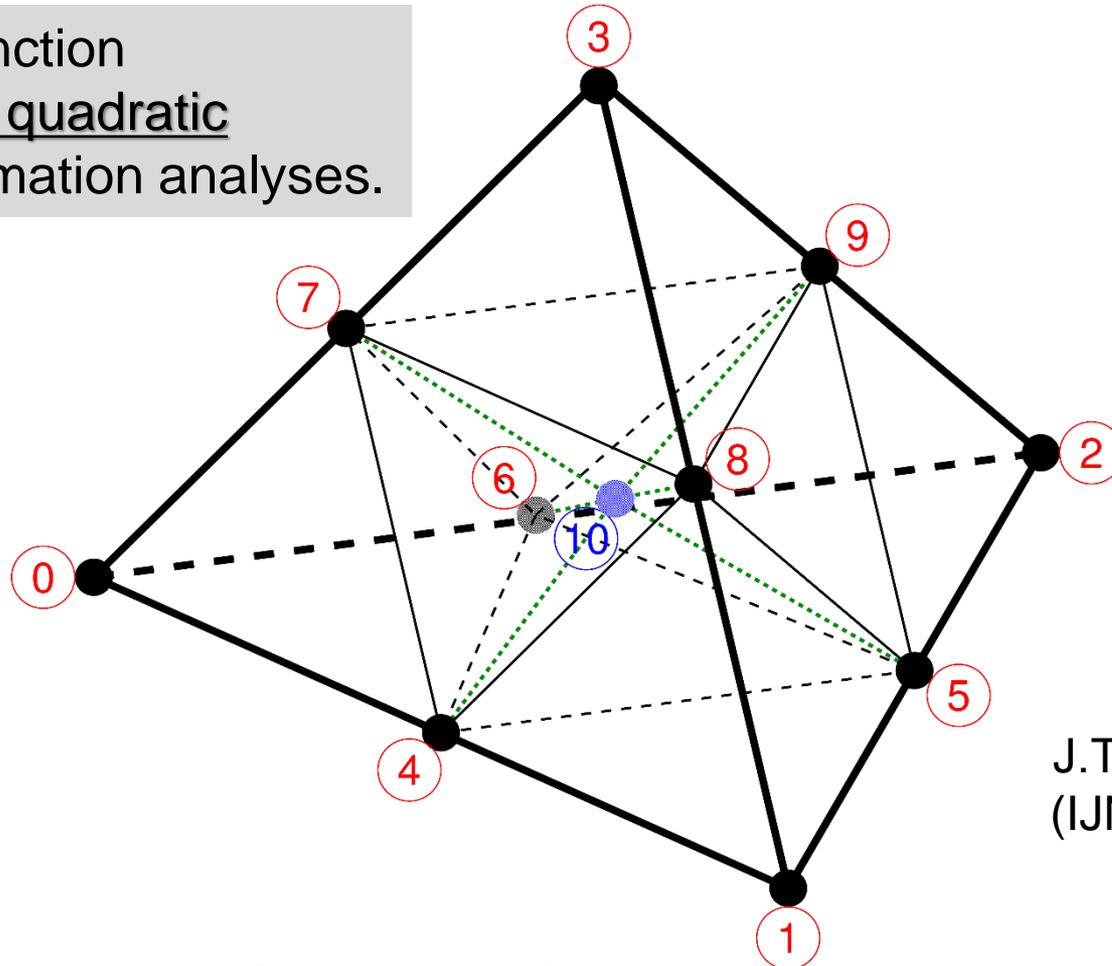
As if putting
an integration point
on each edge center



ES-FEM can avoid shear locking.
However,
it cannot be implemented in
ordinary FE codes due to the
strain smoothing across
multiple elements...

(1) Subdivision into T4 Sub-elements

The shape function should not be quadratic in large deformation analyses.

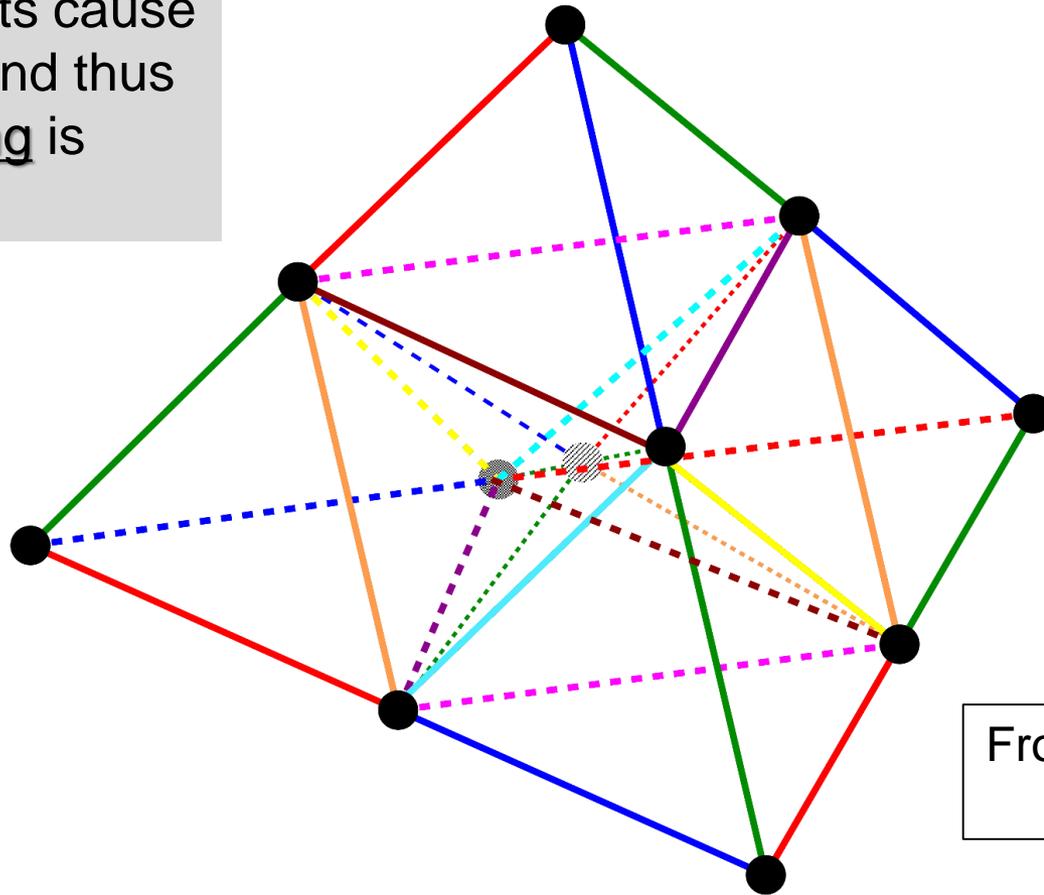


Same as
J.T.Ostien's method.
(IJNME, v107, 2016)

- Put a **dummy node (10)** at the mean location of 6 mid-nodes.
- Subdivide a T10 element into twelve T4 sub-elements and calculate their B -matrices and strains.

(2) Deviatoric Strain Smoothing

T4 sub-elements cause shear locking and thus strain smoothing is necessary.



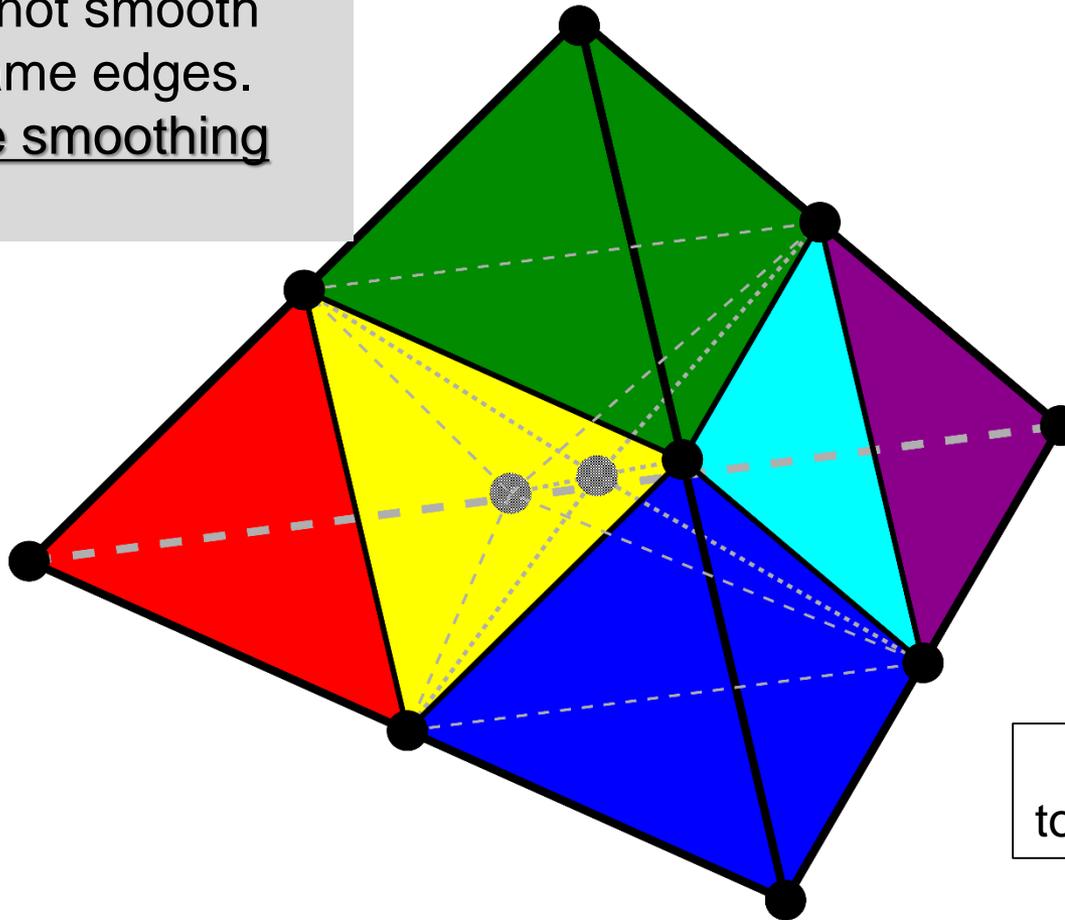
From 12 sub-elements
to 30 edges

- Perform strain smoothing in the manner of **ES-FEM** (i.e., average dev. strains of sub-elements at edges). Then...

(2) Deviatoric Strain Smoothing

(cont.)

ES-FEM does not smooth the strain at frame edges. Thus one more smoothing is necessary.

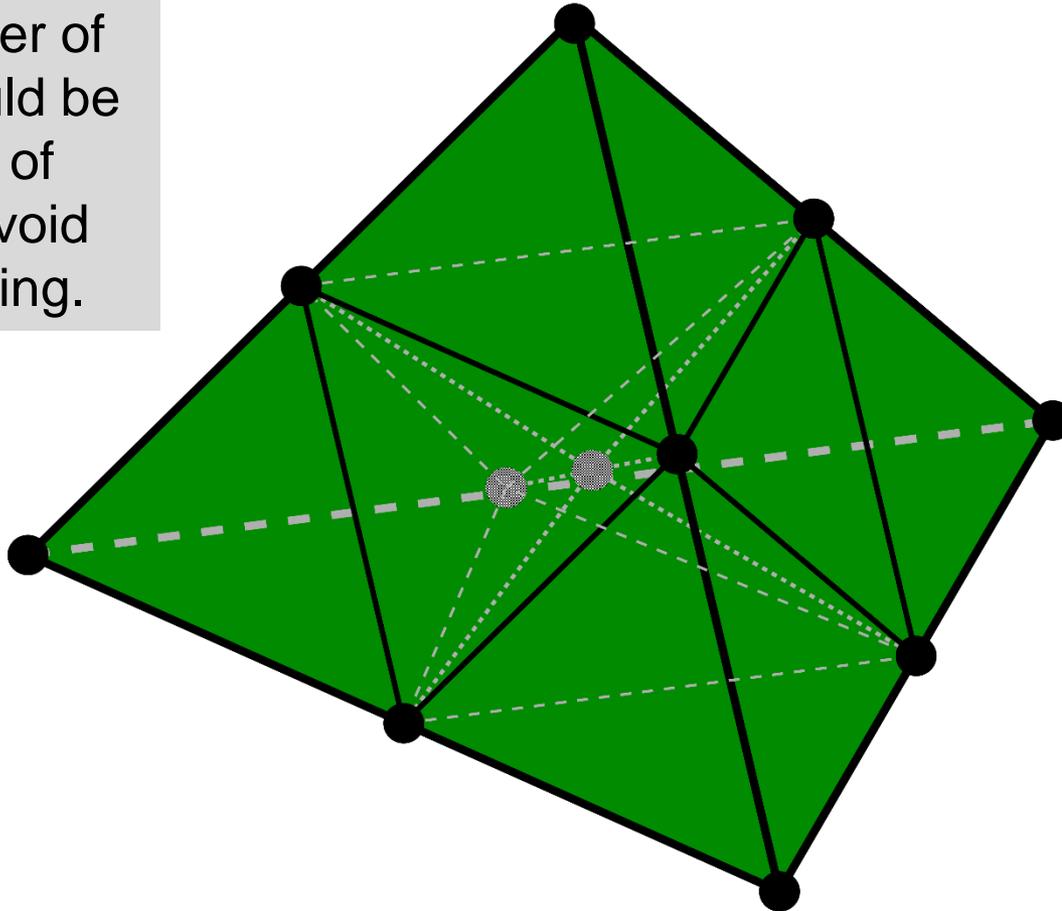


From 30 edges
to 12 sub-elements

- Perform one more strain smoothing in the reverse direction (i.e., average dev. strains of edges at sub-elements), which is so to speak **(ES-FEM)⁻¹**.

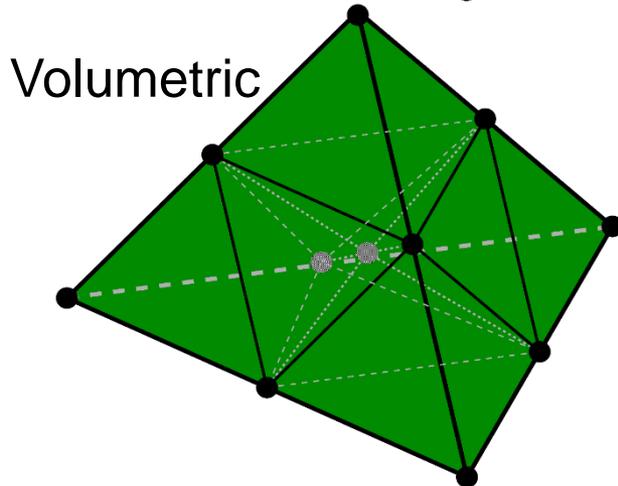
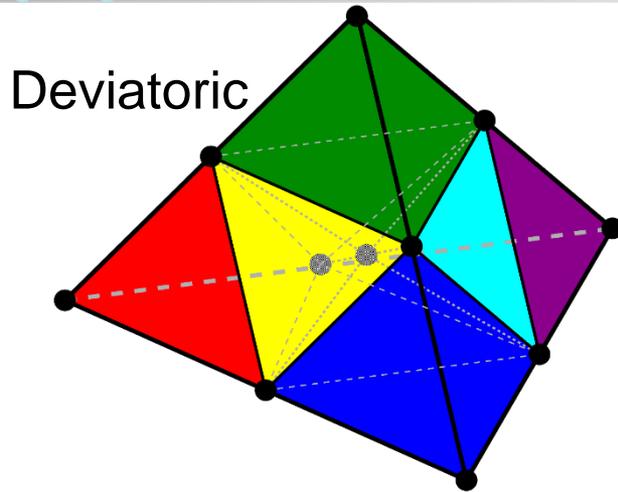
(3) Volumetric Strain Smoothing

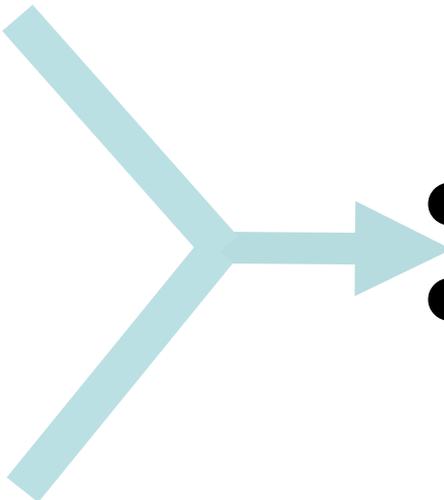
The spatial order of vol. strain should be lower than that of dev. strain to avoid volumetric locking.



- Treat the **overall mean** vol. strain of all sub-elements as the uniform element vol. strain (i.e., same approach as SRI elements).

(4) Combining with SRI Method

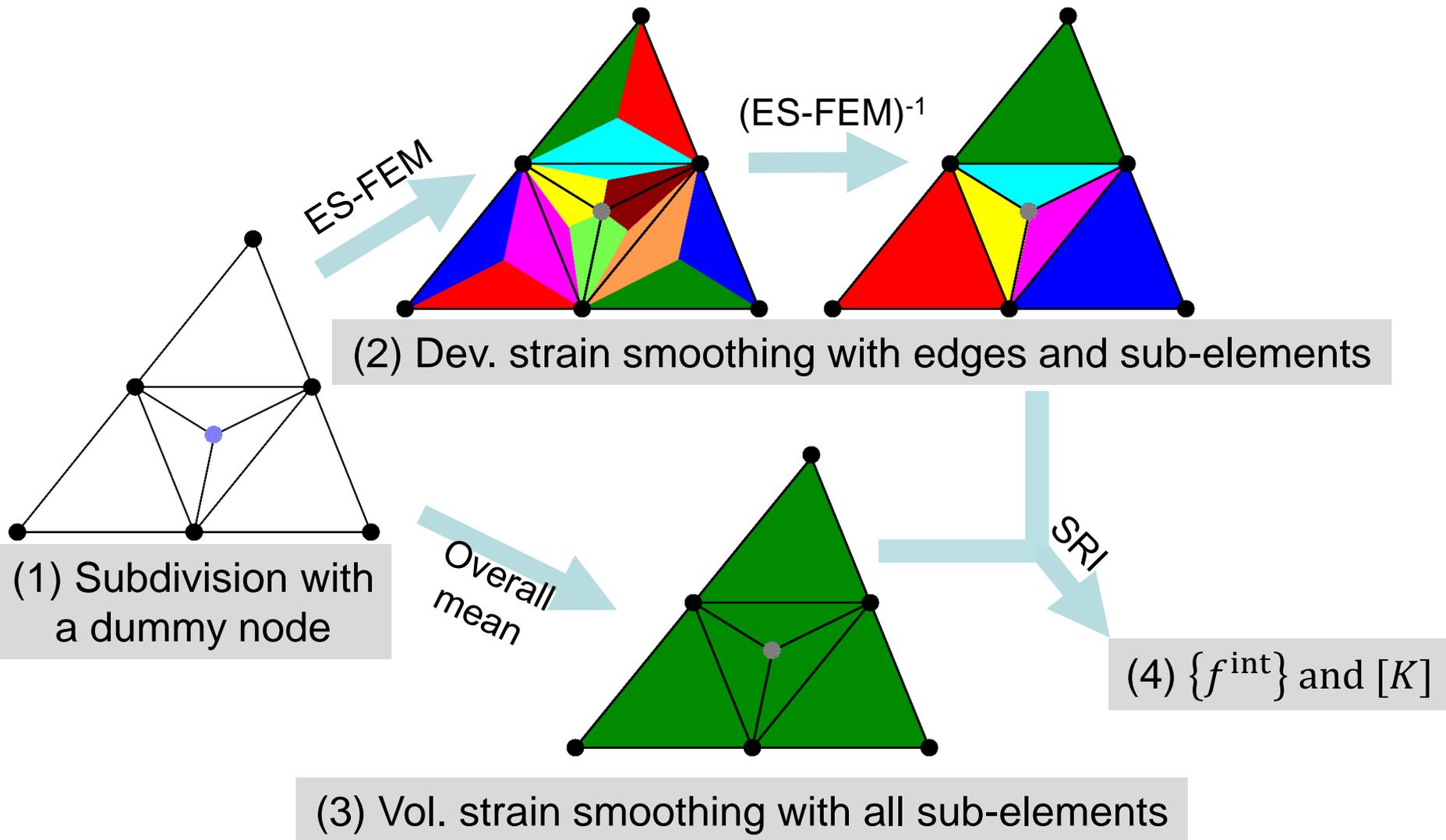


- 
- Internal force $\{f^{\text{int}}\}$
 - Stiffness $[K]$

- Apply **SRI** method to combine the Dev. & Vol. parts and obtain $\{f^{\text{int}}\}$ and $[K]$.

Flowchart of SelectiveCS-FEM

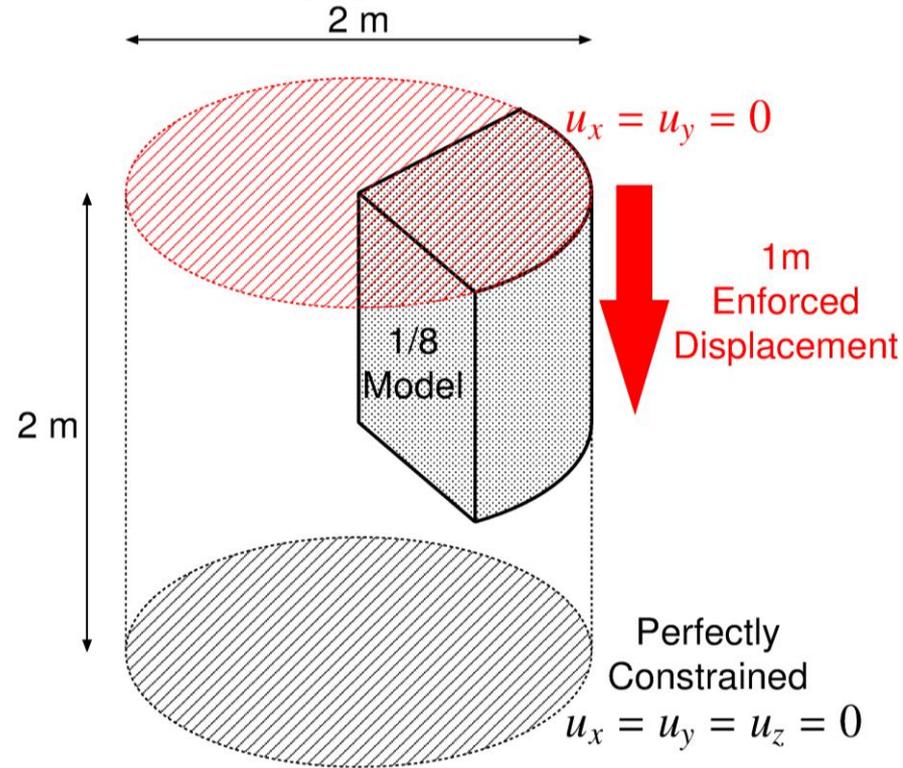
Explanation in 2D (6-node triangular element) for simplicity



Demonstration of SelectiveCS-FEM-T10

Barreling of Hyperelastic Cylinder

Outline



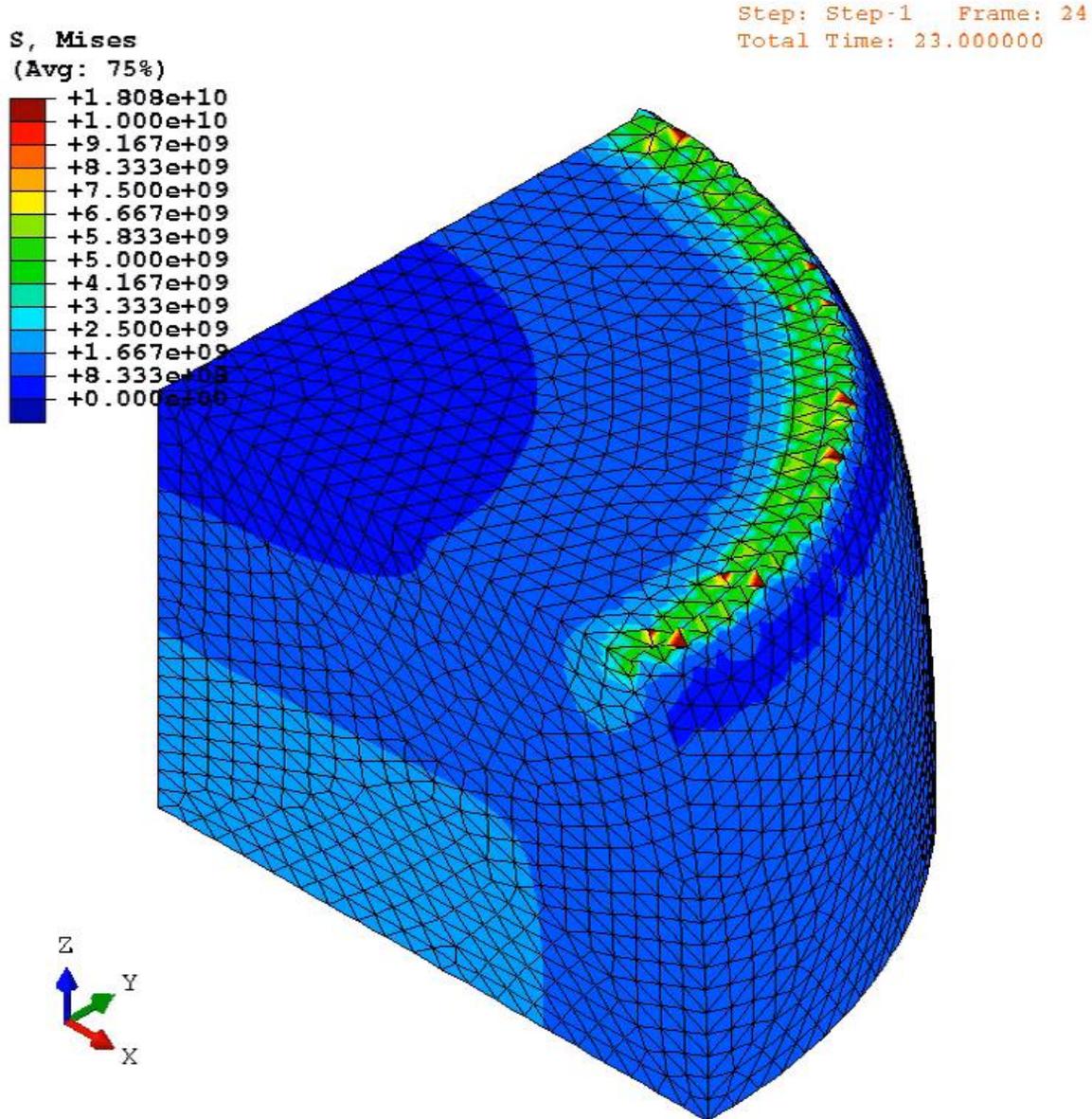
- Enforce **axial displacement** on the top face.
- Neo-Hookean body with $\nu_{ini} = 0.49$.
- Compare results with ABAQUS T10 hybrid elements (C3D10H, C3D10MH, C3D10HS) using the same mesh.

Barreling of Hyperelastic Cylinder

Animation of Mises stress (ABAQUS C3D10MH)

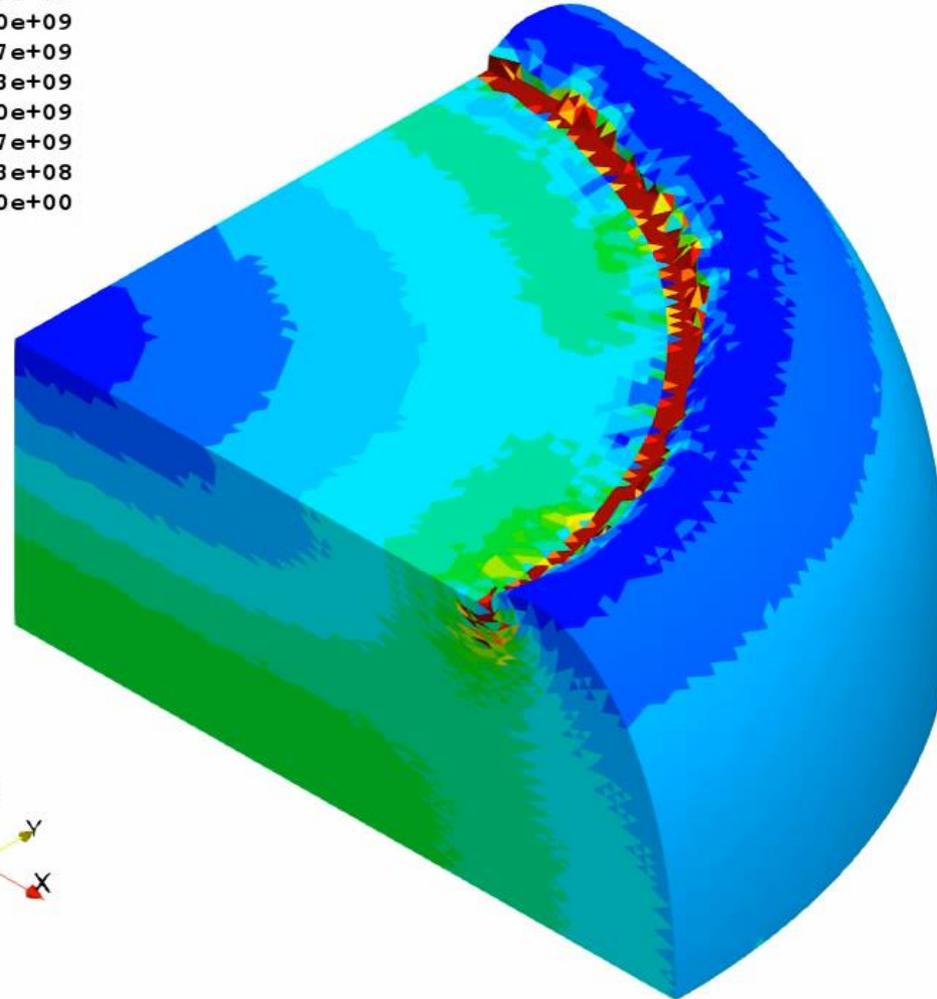
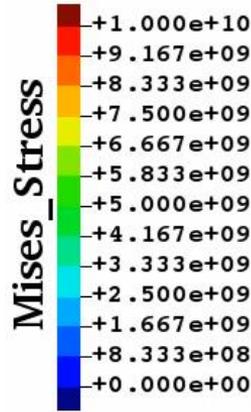
Convergence failure at **24%** compression

Unnaturally oscillating distributions are obtained around the rim.



Barreling of Hyperelastic Cylinder

Animation of Mises stress (Selective CS-FEM-T10)



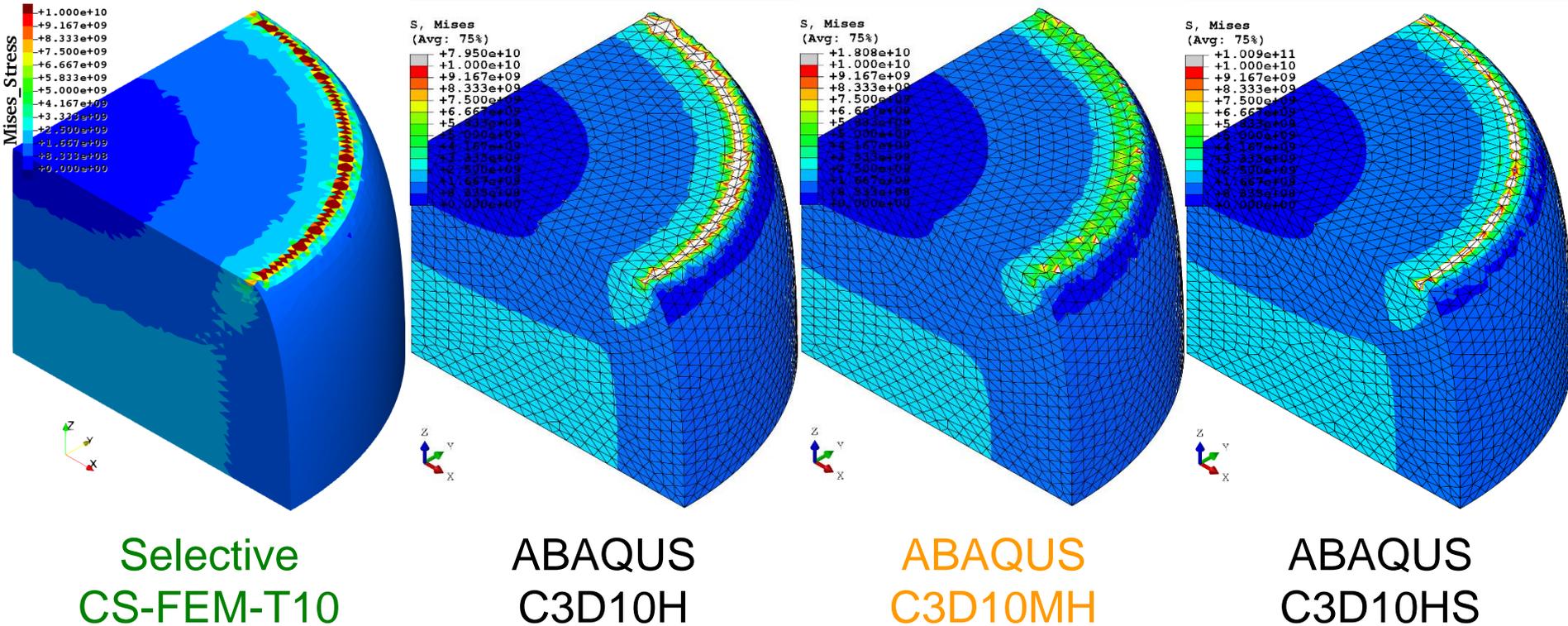
Convergence failure at 47% compression

Smooth distributions are obtained except around the rim.

The present element is more **stable** than ABAQUS C3D10MH

Barreling of Hyperelastic Cylinder

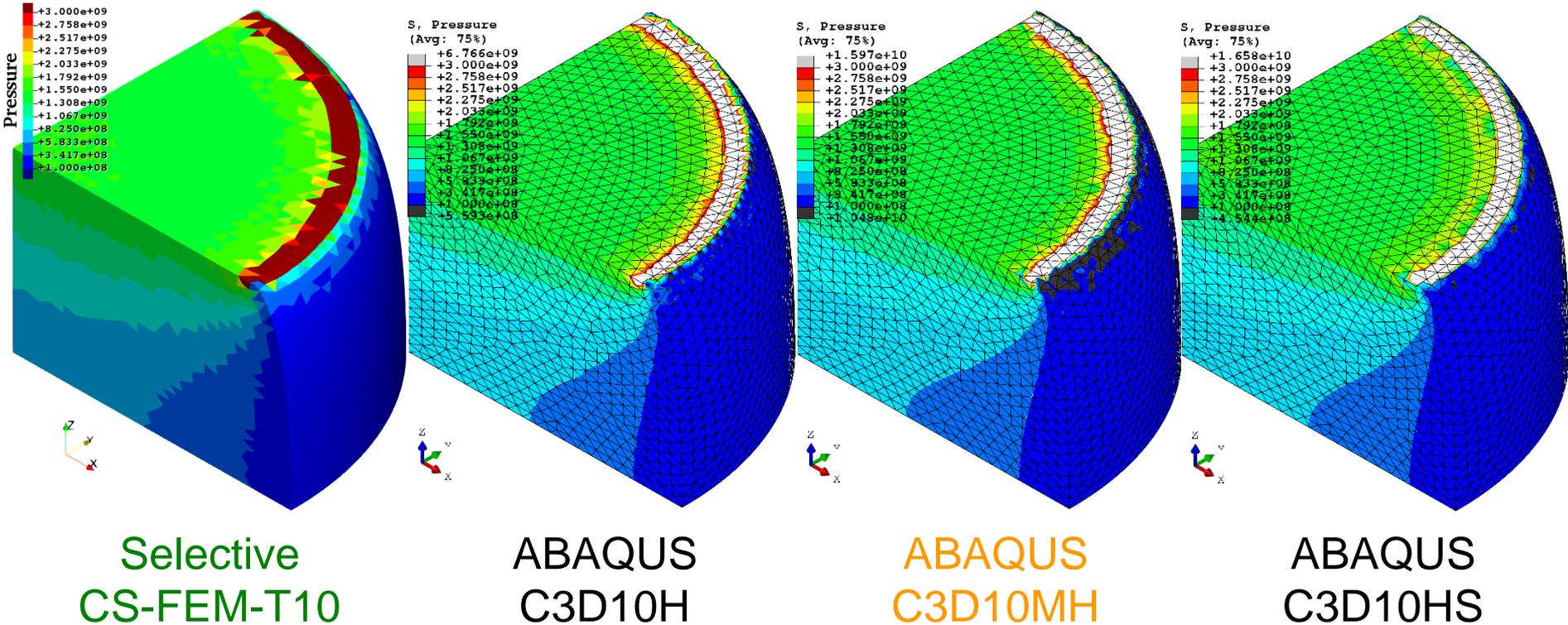
Comparison of Mises stress at 24% comp.



All results are similar to each other except around the rim having stress singularity.

Barreling of Hyperelastic Cylinder

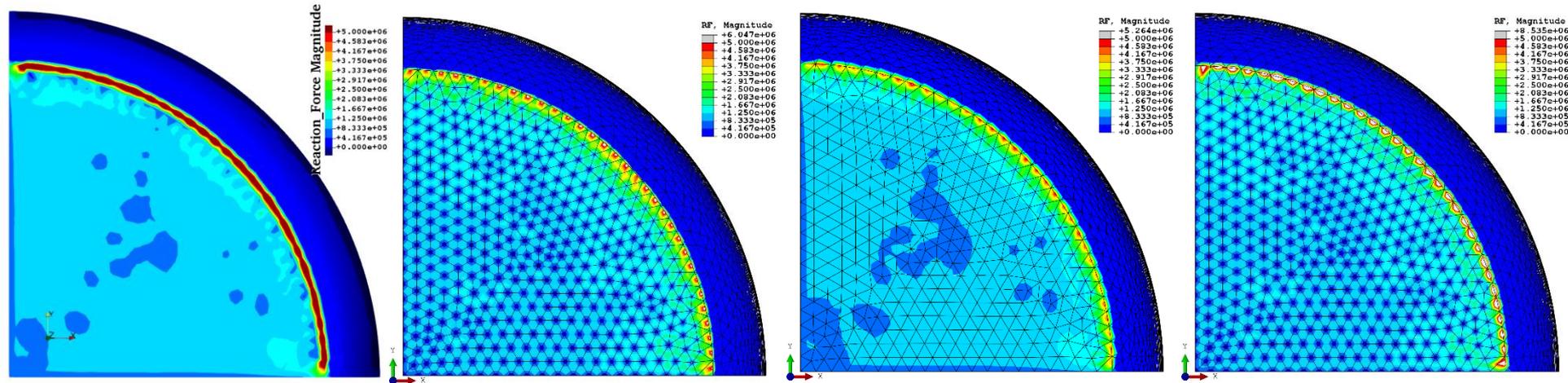
Comparison of pressure at 24% comp.



All results are similar to each other except around the rim having stress singularity.

Barreling of Hyperelastic Cylinder

Comparison of nodal reaction force at 24% comp.



Selective
CS-FEM-T10

ABAQUS
C3D10H

ABAQUS
C3D10MH

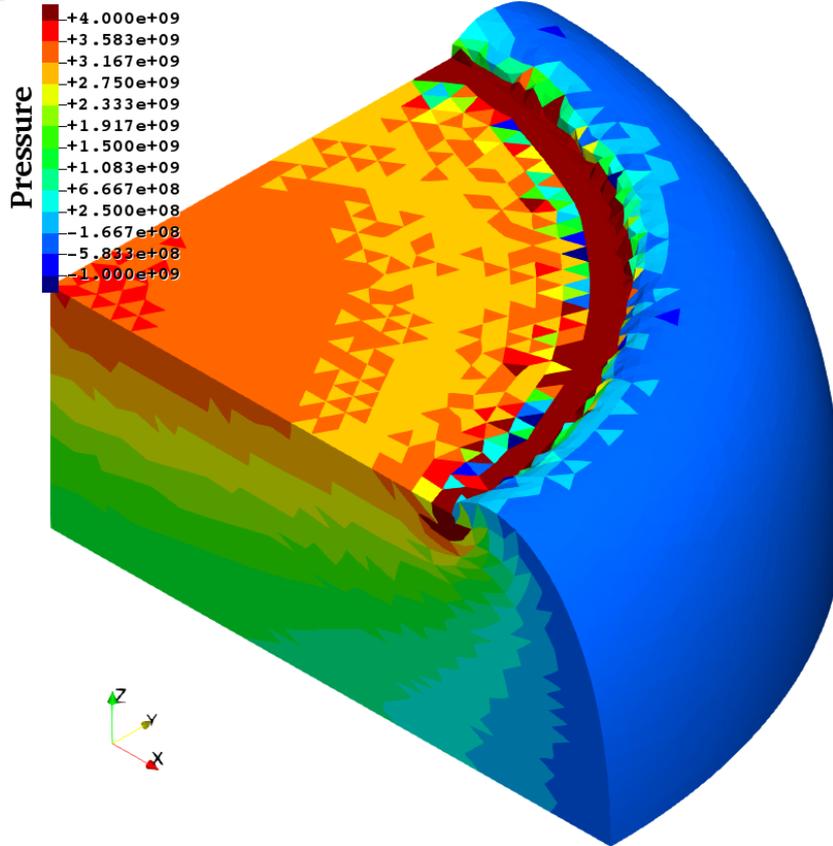
ABAQUS
C3D10HS

ABAQUS C3D10H and C3D10HS
suffer from nodal force oscillation.

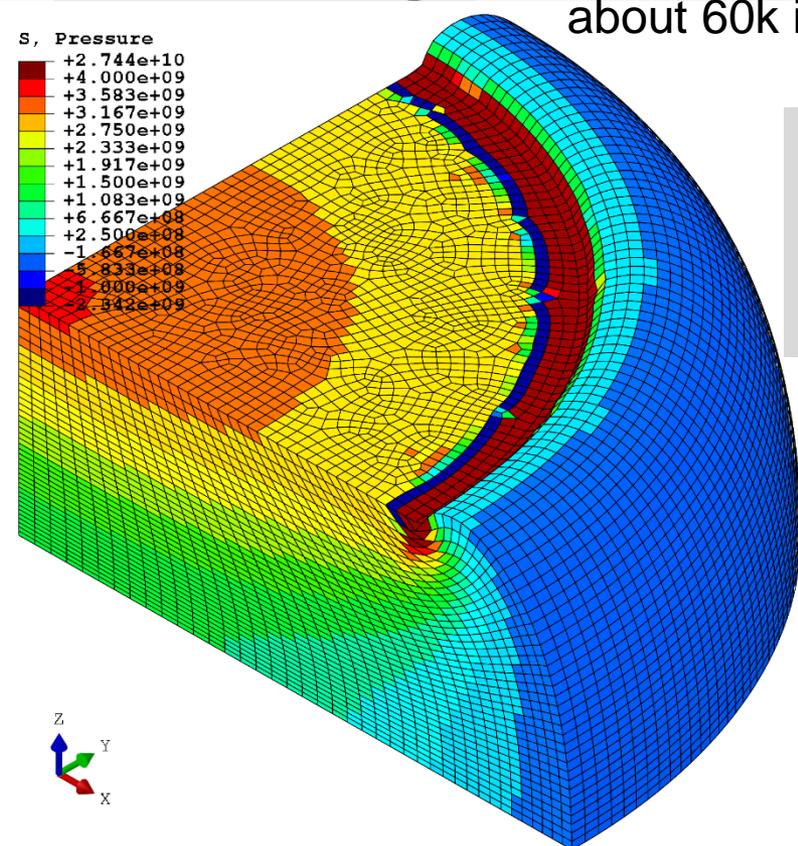
Barreling of Hyperelastic Cylinder

Comparison of pressure at 47% comp.

of nodes are about 60k in both.



SelectiveCS-FEM-T10



ABAQUS C3D8

Conv. failure at 50% comp.

The present element has competitive accuracy and stability as much as H8-SRI element.

Implementation of SelectiveCS-FEM-T10 into ABAQUS

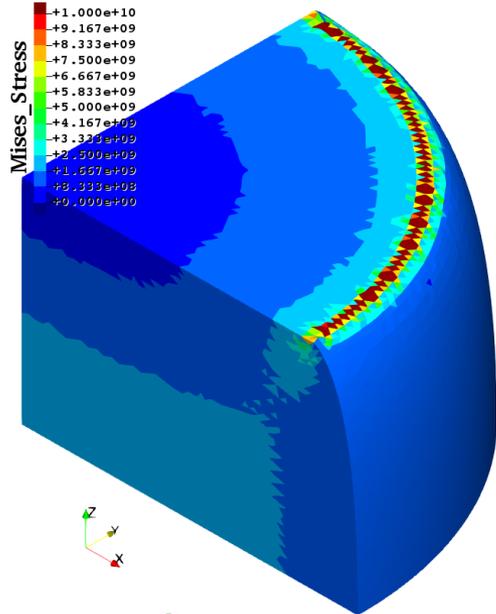
Brief of ABAQUS UEL

- ABAQUS has functionality of “**u**ser-defined **e**lement” (simply called “**UEL**”).
- UEL is usually written in Fortran77, but in fact it can be written in **Fortran90**.
- Coding a subroutine named “UEL” and compiling it, one can execute ABAQUS using one’s own element:

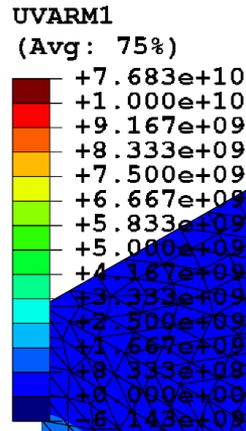
```
% abaqus job=test user=my_uel.o
```
- Analysis results can be visualized on ABAQUS Viewer by defining **overlap elements** with zero stiffness in the “inp” file.

Results of ABAQUS UEL

Comparison of Mises stress (24% comp.)



Selective
CS-FEM-T10
of in-house code



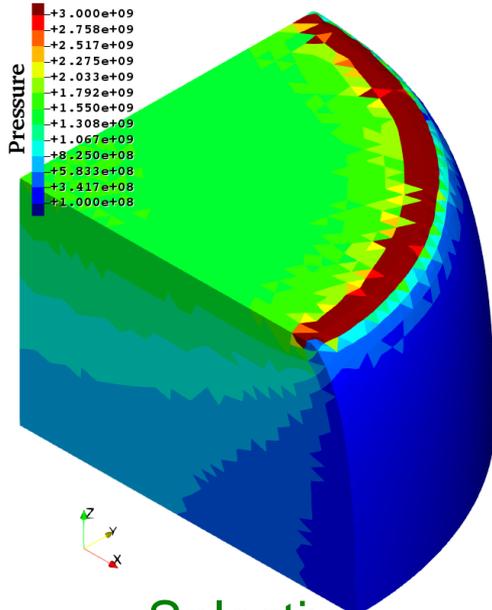
Selective
CS-FEM-T10
of ABAQUS UEL

Well
agreed
with
in-house
code.

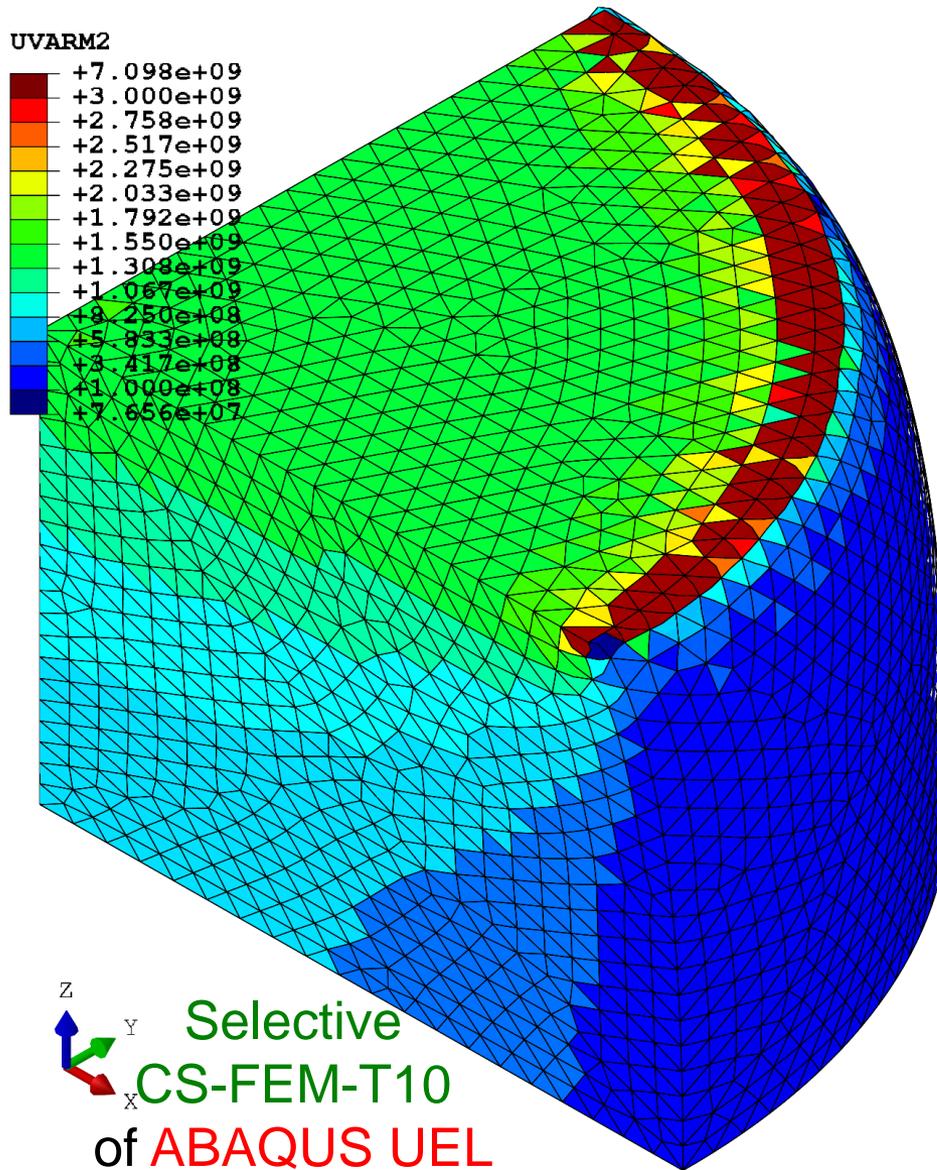
Small
difference
comes
from the
difference
of mapping
calculation.

Results of ABAQUS UEL

Comparison of pressure (24% comp.)



Selective
CS-FEM-T10
of in-house code



Selective
CS-FEM-T10
of ABAQUS UEL

Well
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code.

Small
difference
comes
from the
difference
of mapping
calculation.

Issues in ABAQUS UEL

- We have to define the overlap elements
 - to visualize the results with ABAQUS Viewer.
 - to define element-based surface for pressure loading, contact pair definition etc..
- The overlap elements cause convergence failure in large deformation analysis.
i.e., the cylinder barreling analysis stops at 24% compression when the overset elements are defined.



Native implementation is essential for the full use of SelectiveCS-FEM-T10, unfortunately...

Summary

Summary of SelectiveCS-FEM-T10

Benefits

- ✓ Locking-free.
- ✓ No pressure checkerboarding.
- ✓ No nodal force oscillation.
- ✓ No increase in DOF.
- ✓ Long lasting in large deformation.
- ✓ Same CPU cost as the standard T10 elements.

Drawbacks

- ✗ No longer a T4 formulation.

Take-home message

Please consider implementing SelectiveCS-FEM-T10 to your in-house code. It's supremely useful & easy to code!!

Thank you for your kind attention!